Model selection and cross validation

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Statistical inference and modeling

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2 Resampling method: Cross validation

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- bias and variance
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Model selection

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Factors in model selection

objective: obtain a good model at a low cost

- **1 quality of the model:** defined by a measure of the goodness, e.g., the mean-squared error, log-likelihood
 - MSE consists of a bias and a variance contribution
 - a complex model has small bias but higher variance (than a simple model)
 - the best model structure is therefore a trade-off between *flexibility* and *parsimony*
- **2** price of the model: an estimation method (which typically results in an optimization problem) highly depends on the model structures, which influences:
 - algorithm complexity
 - properties of the loss function
- 3 intended use of the model: prediction, controller design, inference

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Bias-variance decomposition

assume that the observation \boldsymbol{Y} obeys

$$Y = f(X) + \nu, \quad \mathbf{E}\nu = 0, \quad \mathbf{cov}(\nu) = \sigma^2$$

the mean-squared error of a regression fit $\widehat{f}(X)$ at $X=x_0$ is

$$\begin{aligned} \mathsf{MSE} &= \mathbf{E}[(Y - \hat{f}(x_0))^2 | X = x_0] \\ &= \sigma^2 + [\mathbf{E}\hat{f}(x_0) - f(x_0)]^2 + \mathbf{E}[\hat{f}(x_0) - \mathbf{E}\hat{f}(x_0)]^2 \\ &= \sigma^2 + \mathsf{Bias}^2(\hat{f}(x_0)) + \mathsf{Var}(\hat{f}(x_0)) \end{aligned}$$

- this relation is known as bias-variance decomposition
- \blacksquare no matter how well we estimate $f(x_0),\,\sigma^2$ represents irreducible error
- typically, the more complex we make model \hat{f} , the lower the bias, but the higher the variance

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Proof of bias-variance decomposition

note that

- the true f is deterministic
- $\operatorname{var}(Y|X = x) = \sigma^2$ and $\operatorname{\mathbf{E}}[Y|X = x] = f(x)$ • $\widehat{f}(x)$ is random

we will omit the notation of conditioning on $\boldsymbol{X}=\boldsymbol{x}$

$$\begin{split} \mathbf{E}[(Y - \hat{f}(X))^2] &= \mathbf{E}[Y^2] + \mathbf{E}[\hat{f}(x)^2] - \mathbf{E}[2Y\hat{f}(x)] \\ &= \mathbf{var}(Y) + \mathbf{E}[Y]^2 + \mathbf{var}\,\hat{f}(x) + \mathbf{E}[\hat{f}(x)]^2 - 2f(x)\mathbf{E}[\hat{f}(x)] \\ &= \mathbf{var}(Y) + f(x)^2 + \mathbf{var}\,\hat{f}(x) + \mathbf{E}[\hat{f}(x)]^2 - 2f(x)\mathbf{E}[\hat{f}(x)] \\ &= \sigma^2 + \mathbf{var}\,\hat{f}(x) + (f(x) - \mathbf{E}[\hat{f}(x)])^2 \\ &= \sigma^2 + \mathbf{var}\,\hat{f}(x) + (\mathbf{E}[f(x) - \hat{f}(x)])^2 \\ &= \sigma^2 + \mathbf{var}\,\hat{f}(x) + (\mathbf{E}[f(x) - \hat{f}(x)])^2 \\ &= \sigma^2 + \mathbf{var}\,\hat{f}(x) + [\mathrm{Bias}(\hat{f}(x))]^2 \end{split}$$

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Bias and variance in linear models

two nested linear regression models: predictor X in \mathcal{M}_1 is also contained in \mathcal{M}_2

$$\mathcal{M}_1: y = X\beta$$
 VS $\mathcal{M}_2: y = \begin{bmatrix} X & \tilde{x} \end{bmatrix} \begin{bmatrix} \beta \\ \alpha \end{bmatrix} \triangleq Z\gamma$

setting: two models are estimated by LS method, denoted by $\hat{\beta}$ and $\hat{\gamma}$

- 1 \mathcal{M}_2 has lower MSE in predicting y than the MSE of \mathcal{M}_1
- **2** $\mathbf{cov}(\hat{\beta})$ of \mathcal{M}_2 is larger than $\mathbf{cov}(\hat{\beta})$ of \mathcal{M}_1
- 3 variance of \hat{y} from \mathcal{M}_2 is higher than that of \mathcal{M}_1

 \mathcal{M}_2 (complex model) has less bias but more variance both in estimator and prediction

our proof will use subscript 1 for \mathcal{M}_1 and and 2 for \mathcal{M}_2

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Inverse of block matrices

the inverse of a block matrix

$$X = \begin{bmatrix} A & B \\ C & D \end{bmatrix} \succ 0$$

can be obtained in block using Schur complement: $S = (D - CA^{-1}B)^{-1} \succ 0$

$$X^{-1} = \begin{bmatrix} A^{-1} + A^{-1}B(D - CA^{-1}B)^{-1}CA^{-1} & -A^{-1}B(D - CA^{-1}B)^{-1} \\ -(D - CA^{-1}B)^{-1}CA^{-1} & (D - CA^{-1}B)^{-1} \end{bmatrix}$$
(1)

we often encounter the difference of two quadratic forms

$$\begin{bmatrix} u \\ v \end{bmatrix}^T \begin{bmatrix} A & B \\ B^T & D \end{bmatrix}^{-1} \begin{bmatrix} u \\ v \end{bmatrix} - u^T A^{-1} u = (v - B^T A^{-1} u)^T S^{-1} (v - B^T A^{-1} u) \ge 0$$
 (2)

which is always non-negative

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proof of $MSE_2 \leq MSE_1$

- let P_1 and P_2 be orthogonal projection of y onto $\mathcal{R}(X)$ and $\mathcal{R}(Z)$, resp
- it can be shown that $MSE_1 = \|y\|_2^2 y^T P_1 y$ and $MSE_2 = \|y\|_2^2 y^T P_2 y$ • it is left to show that $y^T P_2 y \ge y^T P_1 y$

$$P_2 = Z(Z^T Z)^{-1} Z^T = \begin{bmatrix} X & \tilde{x} \end{bmatrix} \begin{bmatrix} X^T X & X^T \tilde{x} \\ \tilde{x}^T X & \tilde{x}^T \tilde{x} \end{bmatrix}^{-1} \begin{bmatrix} X^T \\ \tilde{x}^T \end{bmatrix}, \quad P_1 = X(X^T X)^{-1} X^T$$

apply the inverse of block matrix

$$P_2 - P_1 = (\tilde{x} - X(X^T X)^{-1} X^T \tilde{x}) S^{-1} (\tilde{x} - X(X^T X)^{-1} X^T \tilde{x})^T \succeq 0$$

where $S = \tilde{x}^T \tilde{x} - \tilde{x}^T X(X^T X)^{-1} X^T \tilde{x}$

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proof of $\mathbf{cov}(\hat{\beta}_2) \succeq \mathbf{cov}(\hat{\beta}_1)$

• $\mathbf{cov}(\hat{\beta}_2)$ is the leading (1,1) block of $\mathbf{cov}(\hat{\gamma})$, while $\mathbf{cov}(\hat{\beta}_1) = (X^T X)^{-1}$ • use $\mathbf{cov}(\hat{\gamma}) = (Z^T Z)^{-1}$ and the inverse of block matrix

$$(Z^T Z)^{-1} = \begin{bmatrix} X^T X & X^T \tilde{x} \\ \tilde{x}^T X & \tilde{x}^T \tilde{x} \end{bmatrix}^{-1} \triangleq \begin{bmatrix} A & B \\ B^T & D \end{bmatrix}^{-1} = \begin{bmatrix} A^{-1} + A^{-1} B S^{-1} B^T A^{-1} & \times \\ & \times & \times \end{bmatrix}$$

where $S = D - B^T A^{-1} B \succeq 0$ • $\mathbf{cov}(\hat{\beta}_2)$ is bigger than $\mathbf{cov}(\hat{\beta}_1)$ because

$$\mathbf{cov}(\hat{\beta}_2) - \mathbf{cov}(\hat{\beta}_1) = A^{-1} + A^{-1}BS^{-1}B^TA^{-1} - A^{-1} = A^{-1}BS^{-1}B^TA^{-1} \succeq 0$$

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proof of $\operatorname{var}(\hat{y}_2) \ge \operatorname{var}(\hat{y}_1)$

• suppose
$$\hat{y}_1 = u^T \hat{\beta}$$
 and $\hat{y}_2 = w^T \hat{\gamma}$ where $w = (u, v)$

• we test prediction of y from new regressors u and (u, v)

since the model is simply linear, the variance can be obtained by

$$\begin{aligned} \mathbf{var}(\hat{y}_2) - \mathbf{var}(\hat{y}_1) &= w^T \operatorname{\mathbf{cov}}(\gamma) w - u^T \operatorname{\mathbf{cov}}(\beta) u \\ &= \begin{bmatrix} u \\ v \end{bmatrix}^T \begin{bmatrix} X^T X & X^T \tilde{x} \\ \tilde{x}^T X & \tilde{x}^T \tilde{x} \end{bmatrix}^{-1} \begin{bmatrix} u \\ v \end{bmatrix} - u^T (X^T X)^{-1} u \end{aligned}$$

• the difference is non-negative (using result on page 9)

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Model properties

consider bias and variance of model with different structures



(T. Hastie *et.al. The Elements of Statistical Learning*, Springer, 2010 page 225) a simple model has less flexibility (more bias) but easy to interpret and has less variance

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U-shape of generalization error

models are estimated on training data set and evaluated on test set (unseen data)



- training errors always decrease as model complexity increase
- generalization error initially decreases as model picks up relevant features of data
- however, if the model complexity exceeds a certain degree, the generalization error can rise up again – this is when we observe overfitting

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Observe overfitting on test error



too complex models cannot generalize well on test (unseen) data
overfitting occurs when MSE on test set decreases but starts to rise again

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Does overfitting always occur?



- when the true description is highly nonlinear, test MSE does not significantly increase
- overfitting is apparent when the estimated model is more complex (than it should be) in order to explain a simpler ground-truth model

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Model selection criterion

parsimony principle: among competing models which all explain the data well, the model with the smallest number of parameters should be chosen

a model selction criterion consists of two parts:

loss function + model complexity

- the first term is to assess the quality of the model, e.g., likelihood function, RSS, MSE, Fit Percent $(1 \frac{||y-\hat{y}||}{||y-\hat{y}||}) \times 100\%$
- the second term is to penalize the model order and grows as the number of parameters increases
- we choose the best model as the one with the lowest model selection score

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Model selection scores

model quality: \mathcal{L} : log-likelihood, V: loss function

model complexity: d: effective number of parameters

- Akaike information criterion (AIC): AIC(α) = $-2\mathcal{L}(\alpha) + 2d$
- corrected Akaike information (AICc): AICc(α) = $-2\mathcal{L}(\alpha) + 2d + \frac{2d(d+1)}{N-d-1}$
- Bayesian information criterion (BIC): BIC(α) = $-2\mathcal{L}(\alpha) + d\log N$
- Akaike's final prediction-error criterion (FPE): $FPE(\alpha) = V(\hat{\theta}) \left(\frac{1+d/N}{1-d/N}\right)$

Mallow's
$$C_p$$
: $C_p(\alpha) = \frac{1}{N} \left[\text{RSS}(\alpha) + 2d\hat{\sigma}^2 \right]$
adjusted R^2 : $1 - \frac{\text{RSS}(\alpha)/(N-d-1)}{\text{TSS}/(N-1)}$

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Variable selection in linear regression

model: $\hat{y} = \sum_{k=1}^{n} a_k \cos(kx) + b_k \sin(kx)$ for n = 1, 2, ..., 20 and N = 50



- aim to choose the number of basis function (n)
- set the effective number of parameters d = 2n (the number of sin(kx), cos(kx))
- compute Δ AIC, Δ AICc, Δ BIC (subtracted by its minimum), C_p , adjusted R^2

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- AIC and adjusted R^2 chose a complex model, while AICc and BIC picked 4 basis functions (simpler), and C_p chose 7 basis functions
- train MSE always decreases, as well as, R^2 always increases but the curves have a knee around n = 4

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Choosing AR lag order

fitting AR model of order $p=1,2,\ldots,20$ to unemployment rate time series



$$p$$
-order autoregressive (AR) model

$$y(t) = a_1 y(t-1) + a_2 y(t-2) + \dots + a_p y(t-p) + e(t)$$

parameter: $\beta = (a_1, a_2, \dots, a_p)$ fitting: least-squares

- \blacksquare the effective number of parameters is chosen as d=p
- \blacksquare compute $\Delta \text{AIC}, \ \Delta \text{AICc}, \ \Delta \text{BIC}, \ \text{FPE}, \ \text{train} \ \text{MSE}, \ \text{and} \ \text{Fit} \ \text{Percent}$
- data samples: N = 245, examine two cases: (i) use all data (ii) use only half

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left: use all data right: use half of data



- left: AIC, AICc and FPE tend to choose a higher order model (p = 13) but BIC prefers a simpler model (p = 2)
- right: AICc chose a lower order model when N is halved (sample size was corrected)
- both train MSE and Fit Percent are not good indicators for model selection

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Log-likelihood based scores (AIC, AICc)

AIC, AICc, BIC use negative log-likelihood to indicate model quality

$$\begin{aligned} \mathsf{AIC}(\alpha) &= -2\mathcal{L}(\alpha) + 2d \\ \mathsf{AICc}(\alpha) &= -2\mathcal{L}(\alpha) + 2d + \frac{2d(d+1)}{N-d-1} \\ \mathsf{BIC}(\alpha) &= -2\mathcal{L}(\alpha) + d\log N \end{aligned}$$

AIC is an approximation of Kullback-Leibler (KL) divergence between the true density (f(x) and the model $(g(x|\hat{\theta}))$

$$\begin{split} I(f,g) &= \int f(x) \log(f(x)/g(x|\theta)) dx \\ -\mathcal{L}(\hat{\theta}) + d &\approx \mathbf{E}_{\hat{\theta}}[I(f(x),g(x|\hat{\theta}))] + \text{constant} \end{split}$$

AICc penalizes more on complexity for small N (as quadratic term in d); it approaches AIC for large samples (large N)

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Log-likelihood based score (BIC)

- BIC penalizes more on complexity than AIC (as indicated by $\log N > 2$)
- when model candidates contain a true model, BIC is consistent (probability of choosing the correct model $\rightarrow 1$ as $N \rightarrow \infty$)
- model with minimum BIC \Leftrightarrow model with *highest* posterior density

$$\text{posterior odds} = \frac{P(\mathcal{M}_m | \text{data})}{P(\mathcal{M}_l | \text{data})} = \underbrace{\frac{P(\mathcal{M}_m)}{P(\mathcal{M}_l)}}_{\text{prior}} \cdot \underbrace{\frac{P(\text{data} | \mathcal{M}_m)}{P(\text{data} | \mathcal{M}_l)}}_{\text{Bayes factor}}$$

model prior tells which model is more likely to be preferred (by users)

- when prior is not available (all models have equal probabilities), Bayes factor directly affects the posterior odds
- **BIC** (with -2 factor) is an approximate of Bayes factor (see Hastie et al. book)

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- for nested models \mathcal{M}_1 (complex), \mathcal{M}_2 (simple) with $d(\mathcal{M}_1) = d(\mathcal{M}_2) + m$
 - AIC picks complex model if $\mathcal{L}(\mathcal{M}_1) \mathcal{L}(\mathcal{M}_2) > 2m$ (it's worth to use complex model since model quality improved much more)
 - BIC picks complex model if $\mathcal{L}(\mathcal{M}_1) \mathcal{L}(\mathcal{M}_2) > m \log N$
- improved gap of log-likelihood required by AIC is less than that of BIC; hence, AIC is prone to choosing a complex model more easily than BIC
- for LR (log-likelihood ratio) test, with test statistic

$$2(\mathcal{L}(\mathcal{M}_1) - \mathcal{L}(\mathcal{M}_2)) \sim \mathcal{X}^2(m)$$

- LR test picks \mathcal{M}_1 (complex) if $2\mathcal{L}(\mathcal{M}_1) > 2\mathcal{L}(\mathcal{M}_2)$ by $\mathcal{X}^2_{0.05}(m)$
- for m < 7, we have $2m < \chi^2_{0.05}(m)$; hence, AIC tends to pick a complex model more easily than LR test in this case

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Akaike's final prediction (FPE)

denote $V(\hat{\theta})$ a loss function used in prediction error method (*e.g.*, det or trace of error covariance)

$$\mathsf{FPE}(\alpha) = V(\hat{\theta}) \left(\frac{1 + d/N}{1 - d/N} \right)$$

- model complexity is cooperated in *multiplicative form* (as compared to additive form in AIC, BIC)
- \blacksquare when model output is scalar, $V(\hat{\theta})$ is simply MSE and FPE reduces to

$$\mathsf{FPE} = \frac{1}{N} \sum_{t=1} \varepsilon^2(t, \hat{\theta}) \cdot \frac{1 + d/N}{1 - d/N}$$

• it was shown in Ljung book that FPE is a way to approximate of $\lim_{N\to\infty} \mathbf{E}[V(\theta)]$ (population), which can be estimated using $V(\hat{\theta})$ evaluated on *estimation data*

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 C_p is mostly used in linear regression with d predictors and homoskedastic noise

$$C_p(\alpha) = \frac{1}{N} \left[\text{RSS}(\alpha) + 2d\hat{\sigma}^2 \right]$$

- C_p uses quadratic loss to measure model quality
- ${\rm \ \ } \hat{\sigma}^2$ is an estimate of noise variance using ${\rm \ full}$ model
- **RSS**/N always decreases when d increases; penalty on complexity is put on $2d\hat{\sigma}^2$
- in Hastie et al. book, it showed that C_p is an estimate of test MSE
- other form of C_p exists: $C_p = RSS/\hat{\sigma}^2 + 2d N$ but result in choosing the same d

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Adjusted R^2

 R^2 (coefficient of determination) is based on the decomposition:



 ${\cal R}^2$ is the proportion of the total variation in Y that can be linearly predicted by X

$$R^2 = 1 - rac{\mathrm{RSS}}{\mathrm{TSS}}, \quad \text{adjusted } R^2 = 1 - rac{\mathrm{RSS}(\alpha)/(N-d-1)}{\mathrm{TSS}/(N-1)}$$

 \blacksquare for linear model, $0 \leq R^2 \leq 1$ and always increases for larger models

- $\hfill\blacksquare$ the presence of d penalizes the criterion for the number of predictor variables
- adjusted R^2 increases if the added predictor variables decrease RSS enough to compensate for the increase in d

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Resampling method: Cross validation

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Jitkomut Songsiri Resampling method: Cross validation

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- a process of *repeatedly* drawing samples from a training set and refitting a model on each sample
- we seek for information that would not be obtained from fitting the model only once using the original training sample
- resampling approaches can be computationally expensive but with nowaday technology, it becomes less prohibitive
 - cross-valiation: used in estimation of test error or model flexibility
 - bootstrap: a measure of accuracy of a parameter estimate

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Cross validation

- training error rate: the average error that results from using a trained model (or method) back on the training data set
- test error rate: the average error that results from using a statistical learning method to predict the response on a **new observation**
- training error can be quite different from the test error rate
- **cross validation** can be used to estimate *test error rate* using available data: split into training and validation sets
 - validation set approach
 - leave-one-out cross validation
 - k-fold cross validation

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Splitting data

- training set: used for fitting a model
- validation set: used for predicting the response from the fitted model



- validation set approach or hold out (left): randomly split data
- leave-one-out or LOOCV (middle): leave 1 sample for validation set
- k-fold (right): randomly split data into k folds; leave 1 fold for validation
 - repeat k times where each time a different fold is regarded as validation set and compute MSE₁, MSE₂,..., MSE_k
 - the test error rate is estimated by **averaging** the k MSE's

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Cross validation on polynomial order

 ${\cal N}=500,$ show 7 runs of holdout, and 5-fold



- result of holdout has high variation since it depends on random splitting
- \blacksquare 5-fold results has less variation because MSE is averaged over k folds
- LOOCV requires N loops (high computation cost); MSE_i 's are highly correlated

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Estimate a true test MSE by CV

accuracy of test error rate (on simulation data set): using model of smoothing splines



compute the *true test MSE* (assume to know true f) as a function of complexity

- (left): cv estimates have the correct general U shape but underestimate test MSE
- (center): cv gives overestimate of test MSE at high flexibility
- (right): the true test MSE and the cv estimates are almost identical

Statistical inference and modeling

most of the times we may perform cv on

- a number of statistical methods: and to see which method has the lowest test MSE
- a single statistical method but different flexibilities: and to see which model complexity yield the lowest test MSE

though sometimes cv method underestimate the true test MSE, they can select the correct level of flexibility

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Trade-off for k-fold

examine the unbiasedness and variance of test MSE

method	validation set	loocv	k-fold
computation	less	high	feasible
training samples	ratio e.g. 70:30	n-1	(k-1)n/k
unbiasedness	low	approximately unbiased	intermediate
variance		high	less

- test MSE is calculated by taking the **average** of many MSE's:
- most of MSE's from *loocv* are highly correlated while MSE's of k-fold are less correlated (since loocv uses more overlapped data in training – hence, fitted models are almost identical)
- fact: the sample mean of highly correlated entries has more variance than the sample mean of less correlated entries

conclusion: trade-off between bias and variance when choosing k in k-fold

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Resampling method: Bootstrap

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Bootstrap

a scheme of obtaining distinct data sets by **repeatedly** sampling with **replacement** from the original data set



use each of new sampled data set to compute a new estimate of α (a quantity)

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Illustrated example of the Bootstrap

suppose $\alpha, 1 - \alpha$ are fractions of investment we put in yield returns of X and Y

- we want to minimize $\mathbf{var}(\alpha X + (1 \alpha)Y)$
- one can show that the solution α that minimizes the variance is given by

$$\alpha = \frac{\sigma_Y^2 - \sigma_{XY}}{\sigma_X^2 + \sigma_Y^2 - 2\sigma_{XY}}$$

- we estimate the value of α by using $\hat{\sigma}_Y^2, \hat{\sigma}_X^2, \hat{\sigma}_{XY}$
- we generate 100 paired observations of X and Y and repeat 1000 times to get

$$\hat{\alpha}^{(1)}, \hat{\alpha}^{(2)}, \dots, \hat{\alpha}^{(1000)}$$

(so we have 1,000 data sets from population)

Statistical inference and modeling

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Example

1,000 data sets from population VS 1,000 bootstrap samples



• histograms of $\hat{\alpha}$ from two approaches are similar and the sample means are close

- standard deviations of $\hat{\alpha}$ are 0.083 (1,000 data sets) and 0.087 (bootstrap)
- the box plots of $\hat{\alpha}$ are also quite similar (true α is 0.6)
- we can use bootstrap when we cannot generate new samples from population

Statistical inference and modeling

MATLAB example

boostrap for estimating the histogram and SE of correlation

- \blacksquare we have only 15 samples of GPA and LSAT scores of law-school students
- we want to compute the correlation between GPA and LSAT

```
load lawdata
rng default % For reproducibility
[bootstat,bootsam] = bootstrp(1000,@corr,lsat,gpa);
figure
histogram(bootstat)
se = std(bootstat)
0.1285
% 1000 is the number of bootstrap samples -- specified by
%
```

figure shows the histogram of correlation coefficient between LSAT and GPA



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some figures and examples are taken from

- Chapter 5 in G.James, D. Witten, T. Hastie, and R. Tibshirani, An Introduction to Statistical Learning: with Applications in R, Springer
- Chapter 7 in T. Hastie, R. Tibshirani and J. Friedman, *The Elements of Statistical Learning: Data Mining, Inference and Prediction*, 2nd edition, Springer, 2009